

**ENABLING LONG-TERM FAIRNESS IN DYNAMIC RESOURCE
ALLOCATION**
ACM SIGMETRICS 2023

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June 21, 2023

FAIRNESS IN RESOURCE ALLOCATION — OFFLINE SETTING



agent 1



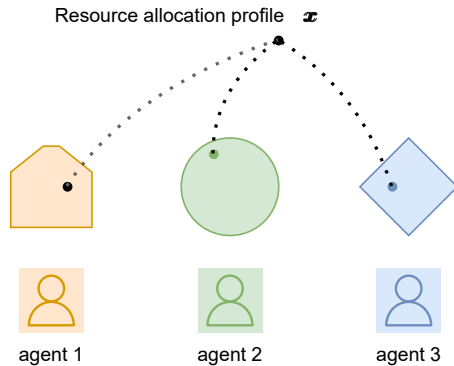
agent 2



agent 3

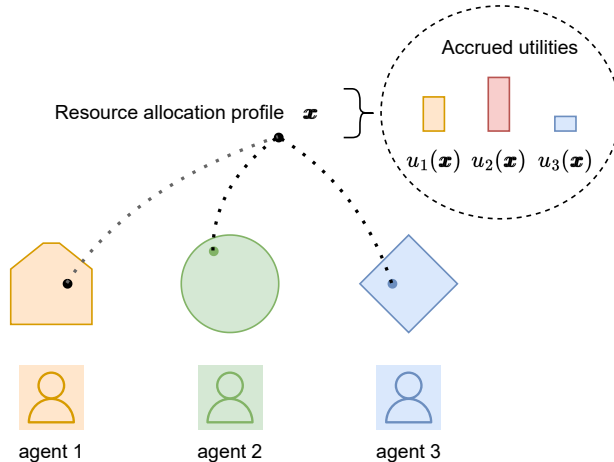
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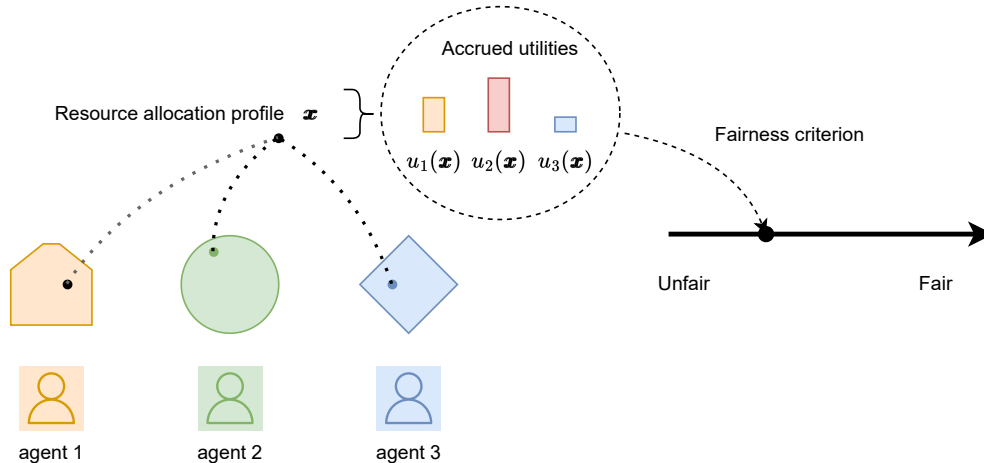
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- ▶ An allocation profile is selected from a convex set $\mathcal{X} = \times_{i \in \mathcal{I}} \mathcal{X}_i$.

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- ▶ The utility of each agent i is a concave function $u_i(\mathbf{x})$.
- ▶ An α -fairness criterion is applied over the vector valued utilities $\mathbf{u}(\mathbf{x}) = (u_i(\mathbf{x}))_{i \in \mathcal{I}}$.

FAIRNESS IN RESOURCE ALLOCATION — OFFLINE SETTING

The α -fairness encompasses the utilitarian principle, proportional fairness (Nash bargaining solution), max-min fairness (Kalai–Smorodinsky bargaining).

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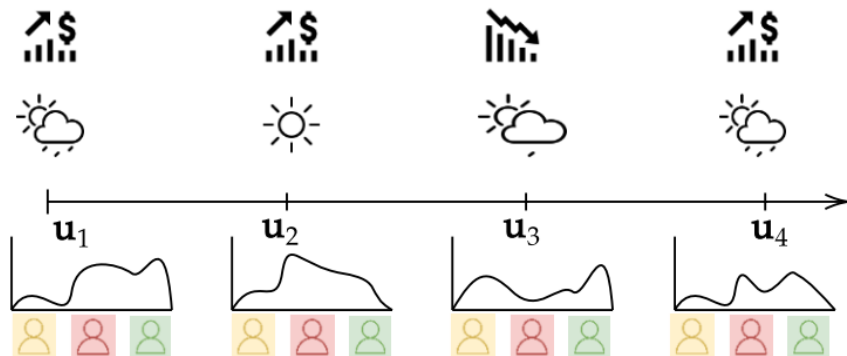
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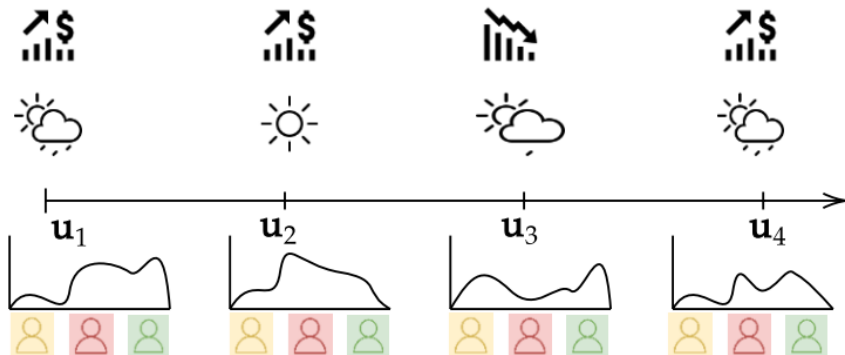
- ▶ Congestion control in the Internet (F.P98; MW00)
- ▶ Selection transmission power in multi-user wireless networks (X. 06; Res06)
- ▶ Allocate multidimensional resources in cloud computing platforms (C. 13; W. 14; T. 15)

FAIRNESS IN RESOURCE ALLOCATION — OFFLINE SETTING



Considering a *static* environment is very often unrealistic for today's communication and computing systems.

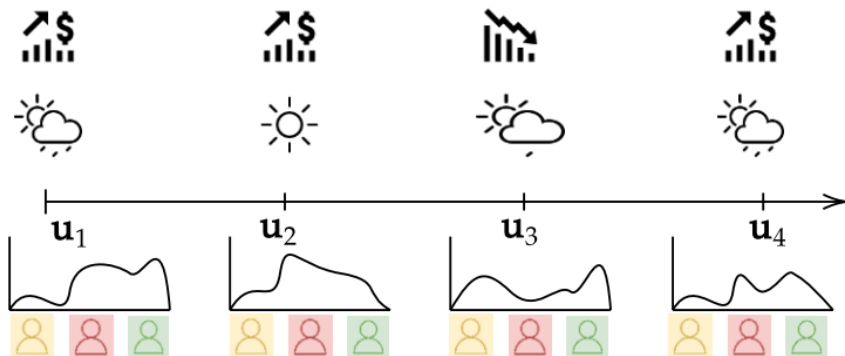
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- ▶ Small-cell mobile networks

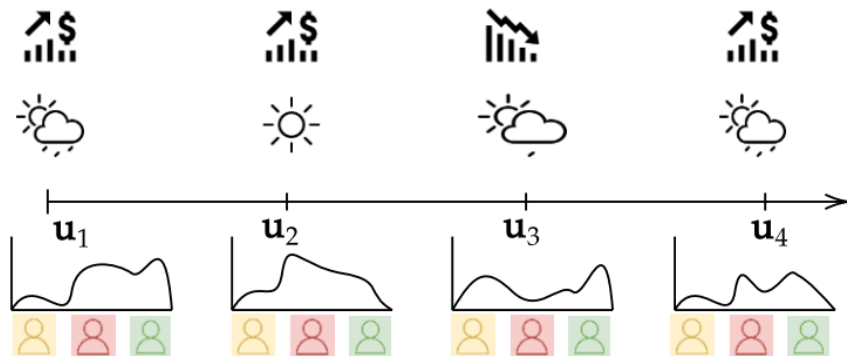
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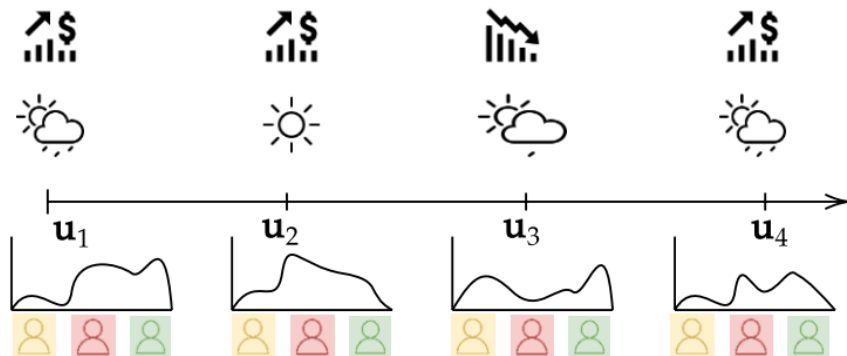
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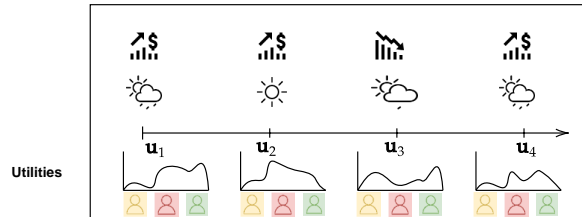
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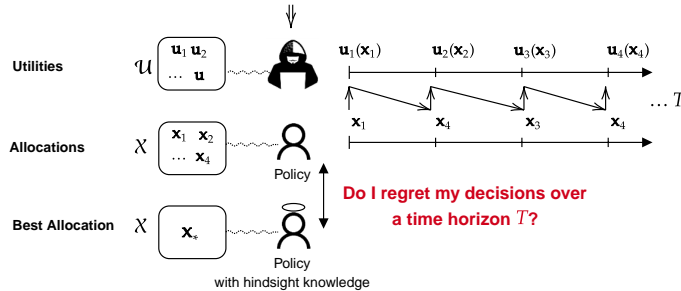
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- ▶ Small-cell mobile networks
- ▶ Placing content files at edge caches
- ▶ Increasing virtualization of communication and computing systems
- ▶ Services driven by user generated data

DYNAMIC SETTING THROUGH ADVERSARIAL ANALYSIS



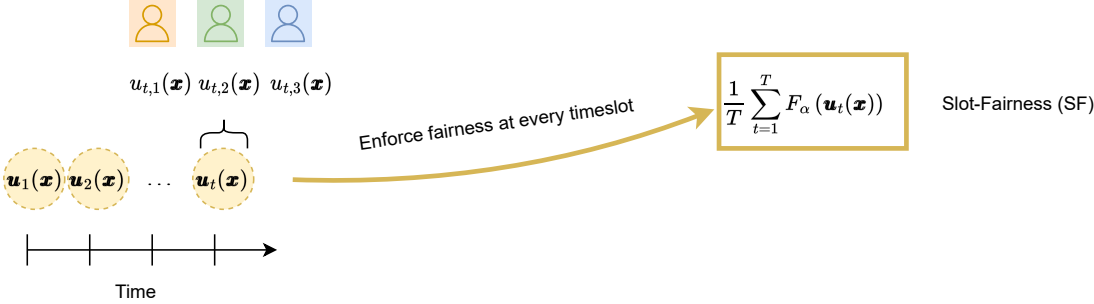
Modeling technique: Noisy unpredictable environment can act as an **adversary** in the worst case scenario



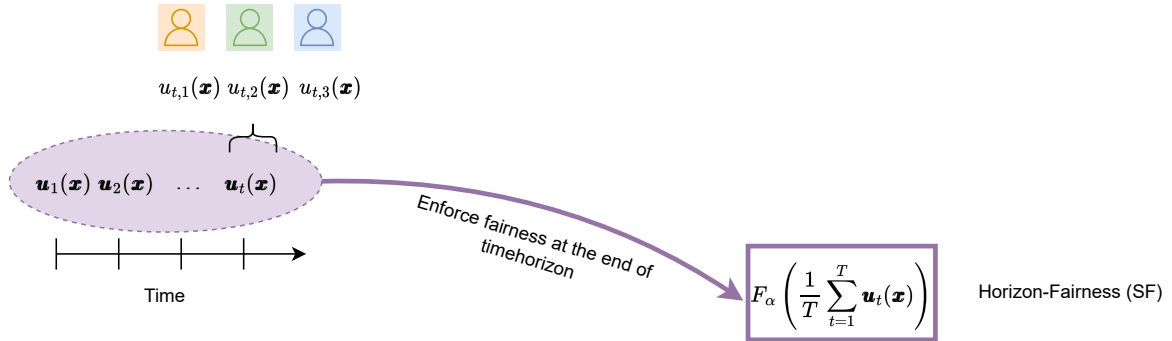
How to Measure Regret?

Describe first how the best allocation is determined.

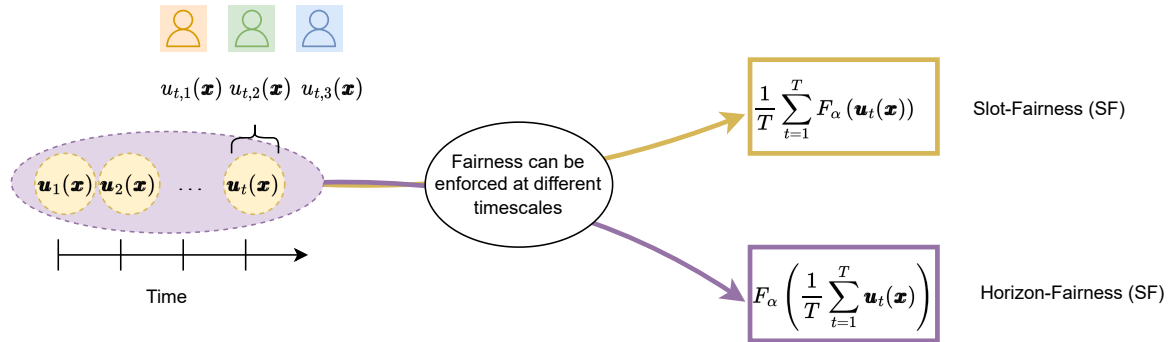
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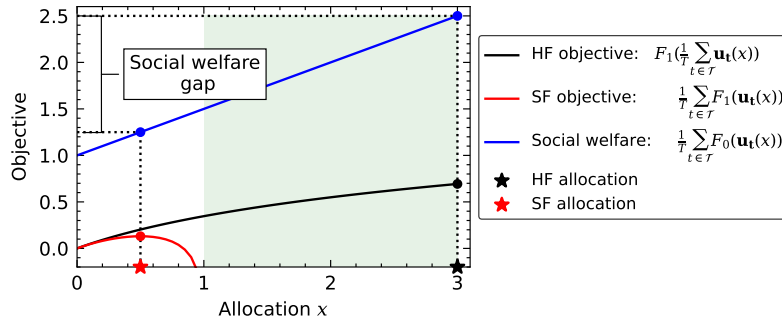
Consider a system with two agents $\mathcal{I} = \{1, 2\}$, an allocation set $\mathcal{X} = [0, x_{\max}]$ with $x_{\max} > 1$, α -fairness criterion with $\alpha = 1$, even $T \in \mathbb{N}$, and the following sequence of utilities

$$\{\mathbf{u}_t(x)\}_{t=1}^T = \{(1+x, 1-x), (1+x, 1+x), \dots\}.$$

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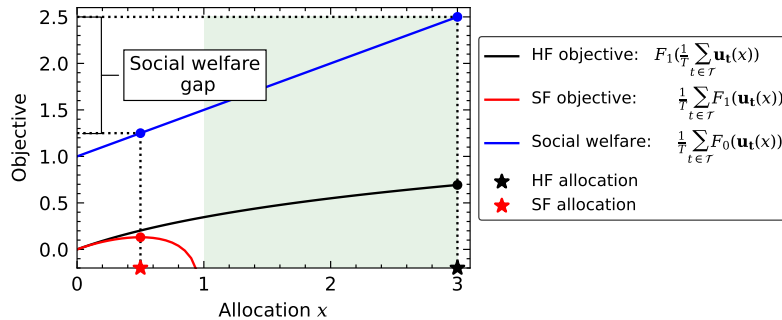
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Horizon-fairness/Slot-Fairness

Slot-Fairness is too restrictive.

FAIRNESS REGRET

We propose the *fairness regret* metric:

Definition

The long-term fairness regret of a policy \mathcal{A} under α -fairness is defined as follows:

$$\mathfrak{R}_T(F_\alpha, \mathcal{A}) \triangleq \sup_{\{\mathbf{u}_t\}_{t=1}^T \in \mathcal{U}^T} \left\{ F_\alpha \left(\frac{1}{T} \sum_{t \in \mathcal{T}} \mathbf{u}_t(\mathbf{x}_*) \right) - F_\alpha \left(\frac{1}{T} \sum_{t \in \mathcal{T}} \mathbf{u}_t(\mathbf{x}_t) \right) \right\}.$$

When $\lim_{T \rightarrow \infty} \mathfrak{R}_T(F_\alpha, \mathcal{A}) = 0$, policy \mathcal{A} will attain the same fairness value as the static benchmark under any possible sequence of utility functions.

IS VANISHING REGRET ACHIEVABLE?

Impossibility Result

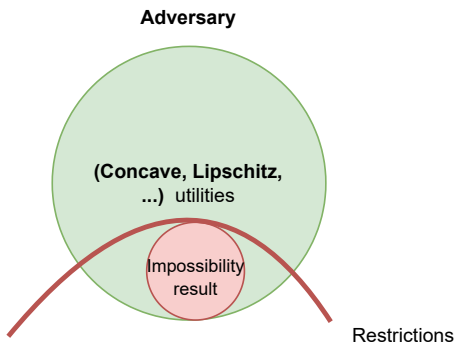
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- ▶ (Proof sketch) We design an adversary with a choice over different sequences of utilities against two agents. No policy can have vanishing fairness regret under all sequences.



OVERCOMING THE IMPOSSIBILITY RESULT

The quantity $\delta_t(\mathbf{x})$ quantifies how much the adversary *perturbs* the average utility at time t , and $\Xi(\mathcal{T})$ is the set of all possible decompositions of \mathcal{T} into sets of contiguous timeslots.

Budgeted-severity:
$$\mathbb{V}_{\mathcal{T}} = \sum_{t \in \mathcal{T}} \sum_{i \in \mathcal{I}} |\delta_{t,i}(\mathbf{x}_*)|,$$

Partitioned-severity:
$$\mathbb{W}_{\mathcal{T}} = \inf_{\substack{\{\mathcal{T}_1, \mathcal{T}_2, \dots, \mathcal{T}_K\} \\ \in \Xi(\mathcal{T})}} \left\{ \sum_{k=1}^K \sum_{i \in \mathcal{I}} \left| \sum_{t \in \mathcal{T}_k} \delta_{t,i}(\mathbf{x}_*) \right| + \sum_{k=1}^K \frac{|\mathcal{T}_k|^2}{\sum_{k' < k} |\mathcal{T}_{k'}| + 1} \right\}.$$

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- The adversary is restricted to select utilities such that: $\min \{\mathbb{V}_{\mathcal{T}}, \mathbb{W}_{\mathcal{T}}\} = o(T)$. These restrictions capture several practical utility patterns, such as non-stationary corruptions, ergodic and periodic inputs (LGK22; BLM22; ZLL⁺19; DAJJ12).

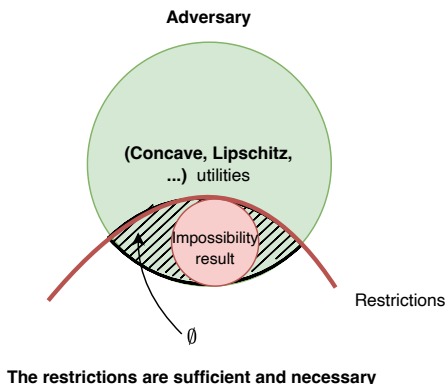
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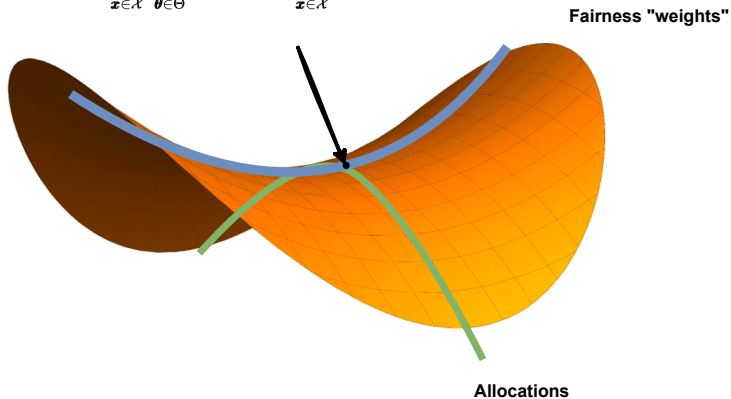
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ONLINE HORIZON FAIR (OHF) POLICY

$$\max_{\mathbf{x} \in \mathcal{X}} \min_{\boldsymbol{\theta} \in \Theta} \Psi(\boldsymbol{\theta}, \mathbf{x}) = \max_{\mathbf{x} \in \mathcal{X}} F_{\alpha}(\mathbf{u}(\mathbf{x}))$$

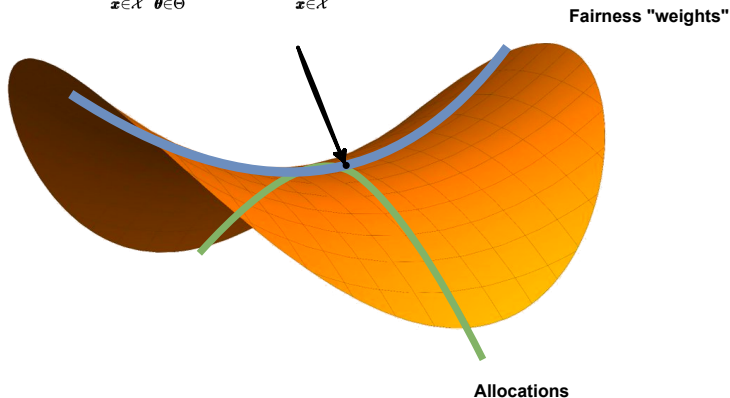


Our policy employs a *time-varying* a convex-concave function:

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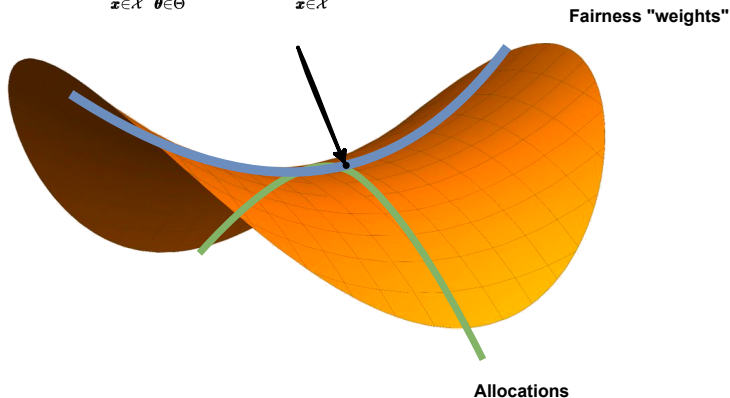
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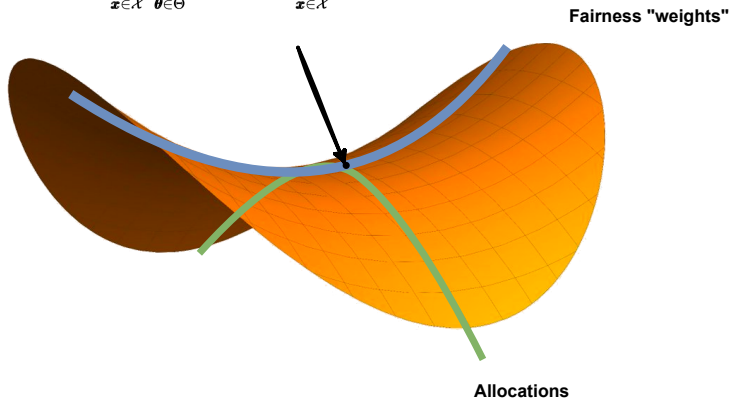
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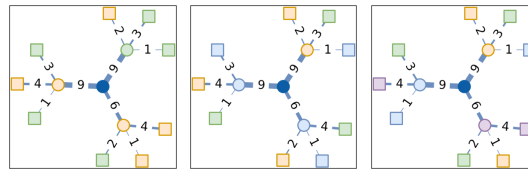
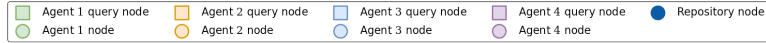
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- ▶ (I) A *convex conjugate* term that tracks the global fairness metric in a dual (conjugate) space
- ▶ (II) A weighted sum of utilities term that tracks the appropriate allocations in the primal space
- ▶ OHF policy attains the following fairness regret guarantee:

$$\mathfrak{R}_T(F_{\alpha}, \mathcal{A}) = \mathcal{O}\left(\frac{1}{\sqrt{T}} + \frac{\min\{\mathbb{V}_{\mathcal{T}}, \mathbb{W}_{\mathcal{T}}\}}{T}\right) = o(1).$$

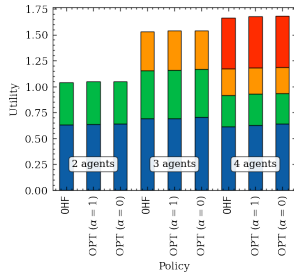
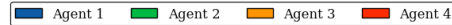
AN APPLICATION — VIRTUALIZED CACHING SYSTEMS



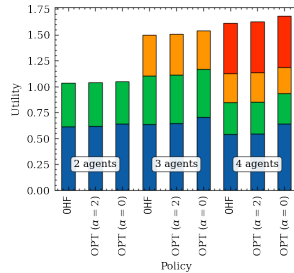
(a) TREE-1

(b) TREE-2

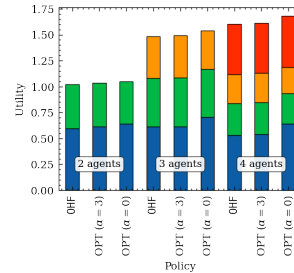
(c) TREE-3



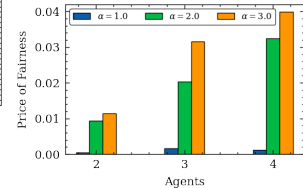
(a) $\alpha = 1$



(b) $\alpha = 2$

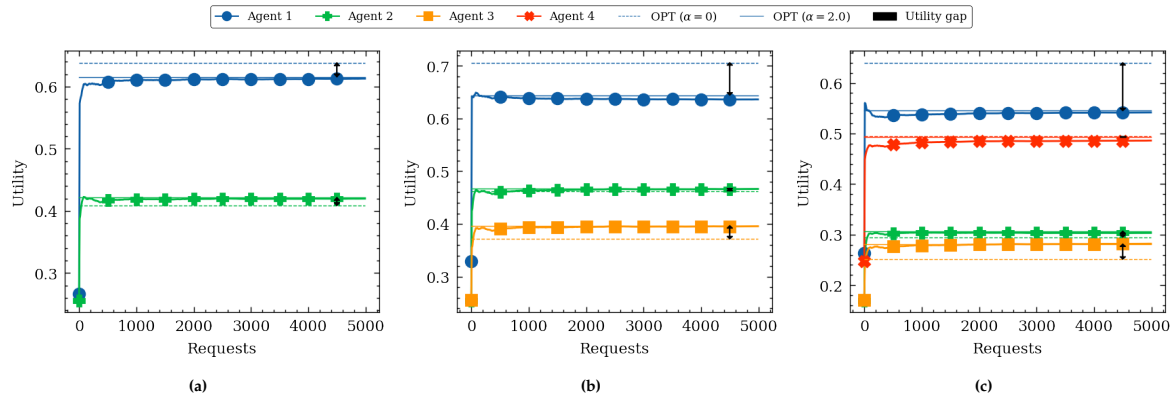


(c) $\alpha = 3$



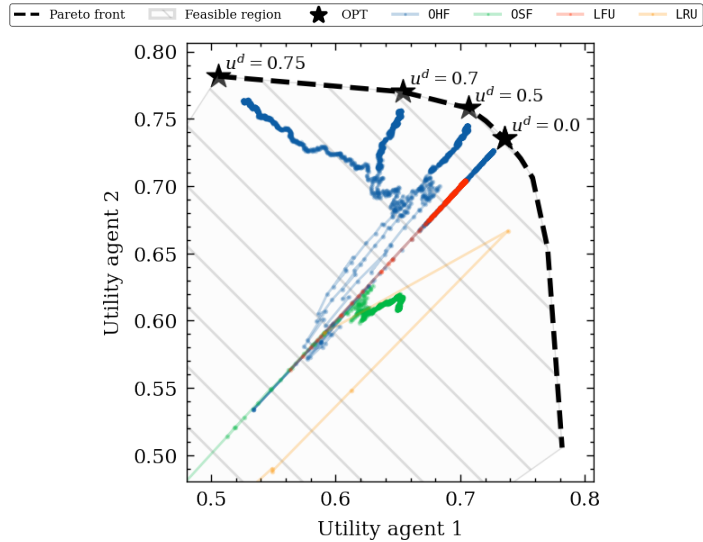
(d) Price of Fairness

AN APPLICATION — VIRTUALIZED CACHING SYSTEMS



The time-averaged utility across different agents obtained by OHF policy and OPT for $\alpha = 2$ under an increasing number of agents in $\{2, 3, 4\}$ and TREE 1–3 network topology.

AN APPLICATION — VIRTUALIZED CACHING SYSTEMS



FUTURE WORK

- ▶ Bridge the horizon-fairness and slot-fairness criteria to target applications where the agents are interested in ensuring fairness within a target time window.
- ▶ Add support for coalition formation in our fairness framework.

Thank You



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